

Amendments to the Claims:

This listing of claims will replace all prior versions, and listings, of claims in the application:

Listing of Claims:

Claim 1 (currently amended) A method of detection in a multiple-input, multiple-output wireless communication system, comprising the steps of:

- (a) receiving a signal representing a set of P symbols, one symbol transmitted from each of P antennas where P is a positive integer greater than 2;
- (b) jointly estimating a subset of P_1 symbols of said set of P symbols where P_1 is a positive integer;
- (c) after step (b), jointly estimating a subset of P_2 symbols of said set of P symbols where P_2 is a positive integer and wherein said subset of P_1 symbols and said subset of P_2 symbols are members of a partition of said set of P symbols and $P_1 + P_2$ is greater than 2.

Claim 2 (original) The method of claim 1, wherein:

- (a) $P_1 = P_2 = P/2$.

Claim 3 (original) The method of claim 1, further comprising:

- (a) after step (c) of claim 1, for each m in the set $\{3, \dots, M\}$, jointly estimating a subset of P_m symbols of said set of P symbols where P_m is a positive integer and wherein said subset of P_m symbols is a member of a partition of said set of P symbols and $P_1 + P_2 + \dots + P_M = P$ where M is a positive integer.

Claim 4 (original) The method of claim 3, wherein:

- (a) $P_1 = P_2 = \dots = P_M = P/M$.

Claim 5 (original) The method of claim 1, wherein:

- (a) said jointly estimating of step (b) of claim 1 includes a decision using P_1 -vector of soft estimates $\mathbf{F}_1 \mathbf{r}$ where \mathbf{r} is a Q -vector of said received signals of step (a) of claim 1 and \mathbf{F}_1 is a $P_1 \times Q$ matrix for zero-forcing estimation;
- (b) said jointly estimating of step (c) of claim 1 includes a decision using P_2 -vector of soft estimates $\mathbf{F}_2 (\mathbf{r} - \mathbf{G}_1 \mathbf{s}^{(1)})$ where \mathbf{F}_2 is a $P_2 \times Q$ matrix for zero-forcing estimation, \mathbf{G}_1 is a $Q \times P_1$ matrix for zero-forcing feedback cancellation, and $\mathbf{s}^{(1)}$ is the P_1 -vector estimation result of step (b) of claim 1.

Claim 6 (original) The method of claim 1, wherein:

- (a) said jointly estimating of step (b) of claim 1 includes a decision using P_1 -vector of soft estimates $\mathbf{F}_1 \mathbf{r}$ where \mathbf{r} is a Q -vector of said received signals of step (a) of claim 1 and \mathbf{F}_1 is a $P_1 \times Q$ matrix for minimum mean square error estimation
- (b) said jointly estimating of step (c) of claim 1 includes a decision using P_2 -vector of soft estimates $\mathbf{F}_2 (\mathbf{r} - \mathbf{G}_1 \mathbf{s}^{(1)})$ where \mathbf{F}_2 is a $P_2 \times Q$ matrix for minimum mean square error estimation, \mathbf{G}_1 is a $Q \times P_1$ matrix for zero-forcing feedback cancellation, and $\mathbf{s}^{(1)}$ is the P_1 -vector estimation result of step (b) of claim 1.

Claim 7 (original) The method of claim 1, wherein:

- (a) said jointly estimating of step (b) of claim 1 includes a decision using P_1 -vector of soft estimates $\mathbf{F}_1 \mathbf{r}$ where \mathbf{r} is a Q -vector of said received signals of step (a) of claim 1 and \mathbf{F}_1 is a $P_1 \times Q$ matrix for minimum mean square error estimation
- (b) said jointly estimating of step (c) of claim 1 includes a decision using P_2 -vector of soft estimates $\mathbf{F}_2 (\mathbf{r} - \mathbf{G}_1 \mathbf{s}^{(1)})$ where \mathbf{F}_2 is a $P_2 \times Q$ matrix for minimum mean square error estimation including feedback error compensation, \mathbf{G}_1 is a $Q \times P_1$ matrix for zero-forcing feedback cancellation including feedback error compensation, and $\mathbf{s}^{(1)}$ is the P_1 -vector estimation result of step (b) of claim 1.

Claim 8 (original) The method of claim 1, wherein:

(a) said subset of P_1 symbols of step (b) of claim 1 is determined according to signal-to-interference-plus-noise ratios of said P symbols prior to a decision in said estimating.

Claim 9 (original) The method of claim 1, wherein:

(a) said subset of P_1 symbols of step (b) of claim 1 is determined according to projected signal-to-interference-plus-noise ratios of said P symbols after a decision in said estimating.

Claim 19 (original) The method of claim 1, wherein:

(a) said jointly estimating of step (b) of claim 1 includes a maximum likelihood decision; and
(b) said jointly estimating of step (c) of claim 1 includes a maximum likelihood decision.

Claim 11 (original) The method of claim 1, wherein:

(a) said jointly estimating of step (b) of claim 1 includes a soft decision; and
(b) said jointly estimating of step (c) of claim 1 includes a soft decision.

Claim 12 (original) The method of claim 1, further comprising:

(a) jointly re-estimating said subset of P_1 symbols using error compensation determined by said jointly estimating said subset of P_2 symbols of step (c) of claim 1.